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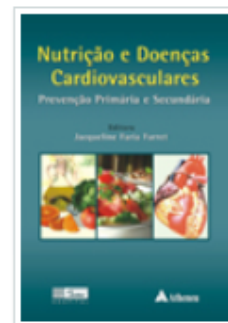
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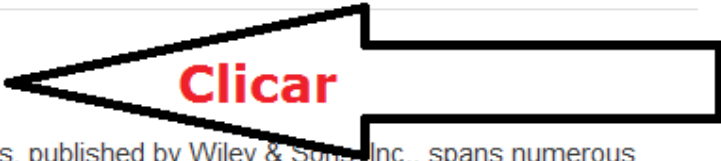
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CHAPTER 1***OPTIMAL SIGNAL PROCESSING
FOR BRAIN-MACHINE
INTERFACES****Justin C. Sanchez and Jose C. Principe***1.1 INTRODUCTION**

Several landmark experimental paradigms have shown the feasibility of using neuroprosthetic devices to restore motor function and control in individuals who are “locked in” or have lost the ability to control movement of their limbs [1–19]. In these experiments, researchers seek to both rehabilitate and augment the performance of neural–motor systems using brain–machine interfaces (BMIs) that transfer the intent of the individual (as collected from the cortex) into control commands for prosthetic limbs and/or computers. Brain–machine interface research has been strongly motivated by the need to help the more than 2 million individuals in the United States suffering from a wide variety of neurological disorders that include spinal cord injury and diseases of the peripheral nervous system [20]. While the symptoms and causes of these disabilities are diverse, one characteristic is common in many of these neurological conditions: Normal functioning of the brain remains intact. If the brain is spared from injury and control signals can be extracted, the BMI problem becomes one of finding *optimal* signal processing techniques to efficiently and accurately convert these signals into operative control commands.

A variety of noninvasive and invasive techniques have been used to collect control

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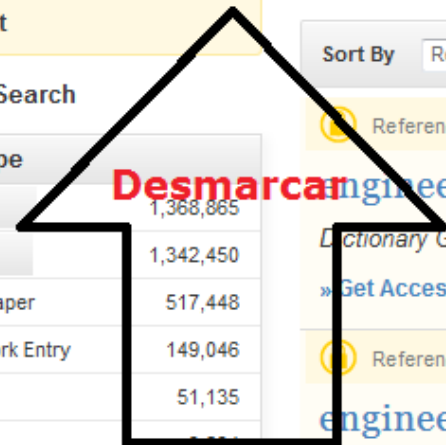


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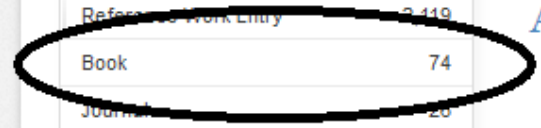


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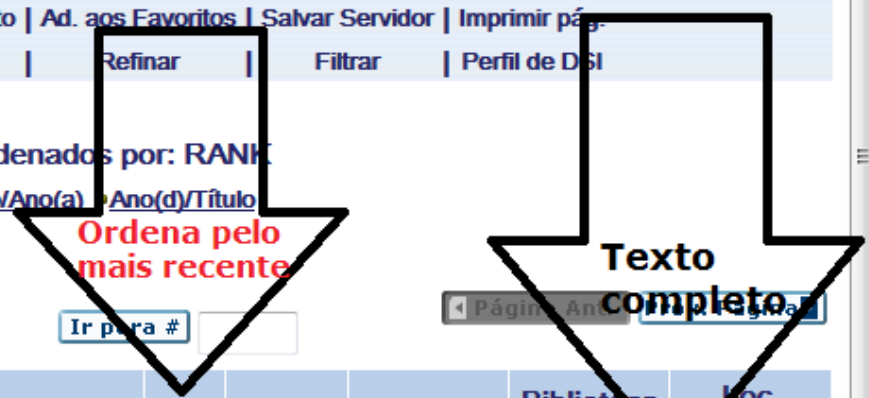
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